



WFF ULDB Mission Design Review

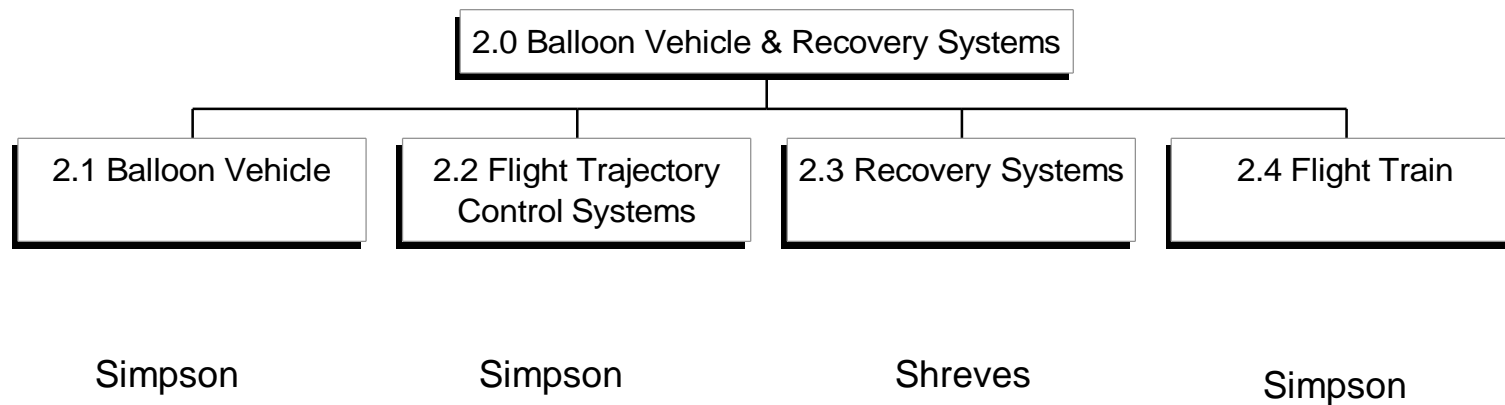
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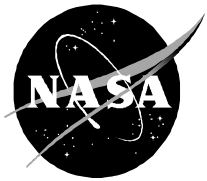
ULDB Balloon Vehicle and Recovery Systems



ULDB Balloon Vehicle & Recovery Systems Products

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ULDB Vehicle and Recovery Systems

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- **Vehicle Structure**
 - Main Envelope
 - Special Structural Elements
- **Flight Trajectory Control Systems**
 - Altitude Control Element
 - Ground Track Control Element
- **Recovery Systems**
 - Descent Element
 - Impact/Containment Elements
- **Flight Train**
 - Load Support/ Separation Element
 - Torque Transfer Element



2.1 Vehicle Structure

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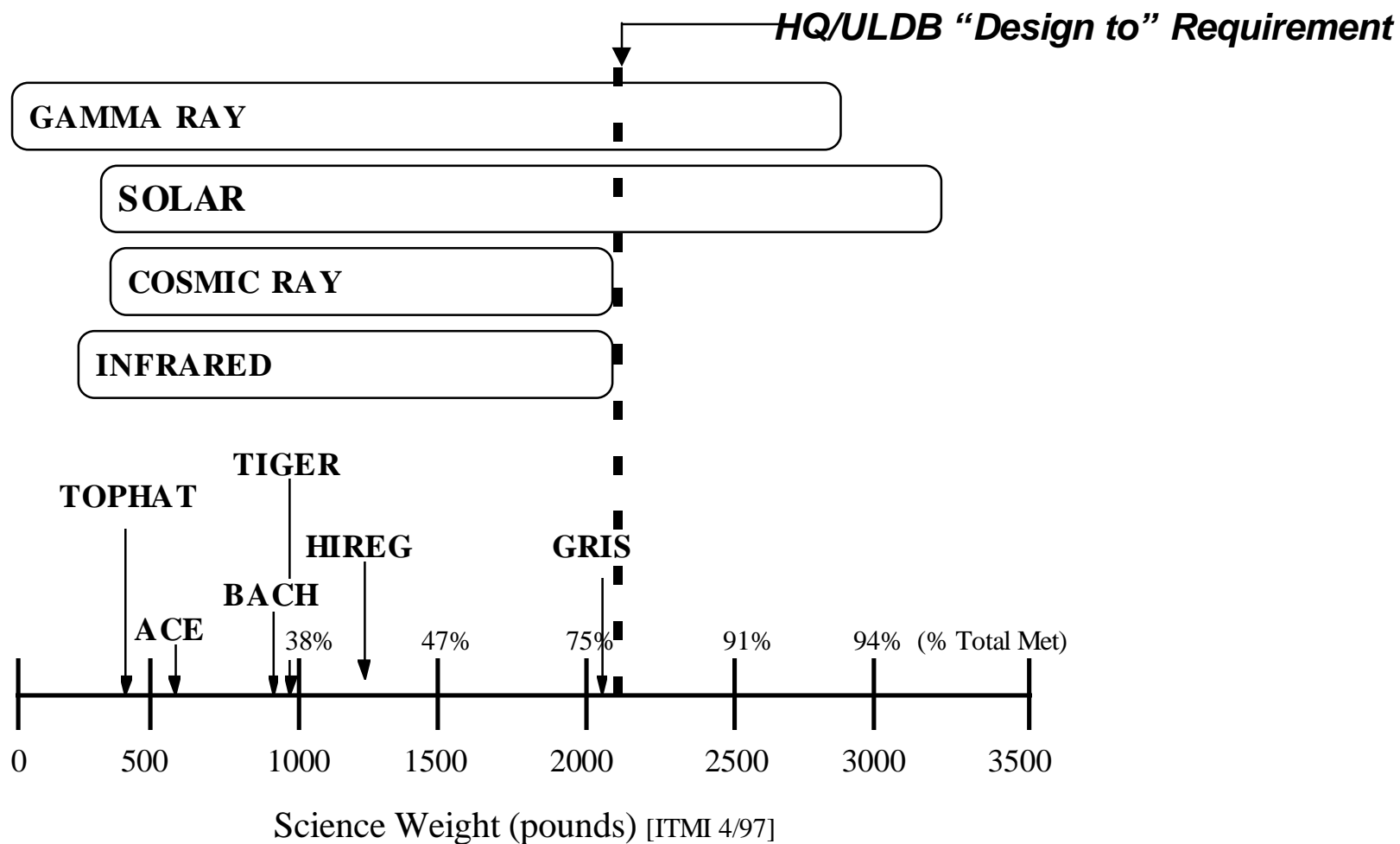
- **Functional Requirements [drivers]**
 - Loft and maintain 'ballooncraft', recovery system and other support elements for up to 100 days Non Polar [Science, Mission, HQ]
 - Achieve minimum float altitudes of 110,000' (33.5 km) to 115,000' (35 km) [HQ, Science]
- **Target Design-to Requirements**
 - Suspended Science Weight to 2200 lb. (1000 kg)
 - Total Suspended Weight to 3500 lb. (1600 kg)
 - Minimum Float Altitude \geq 115,000'



Vehicle Science Weight Requirements

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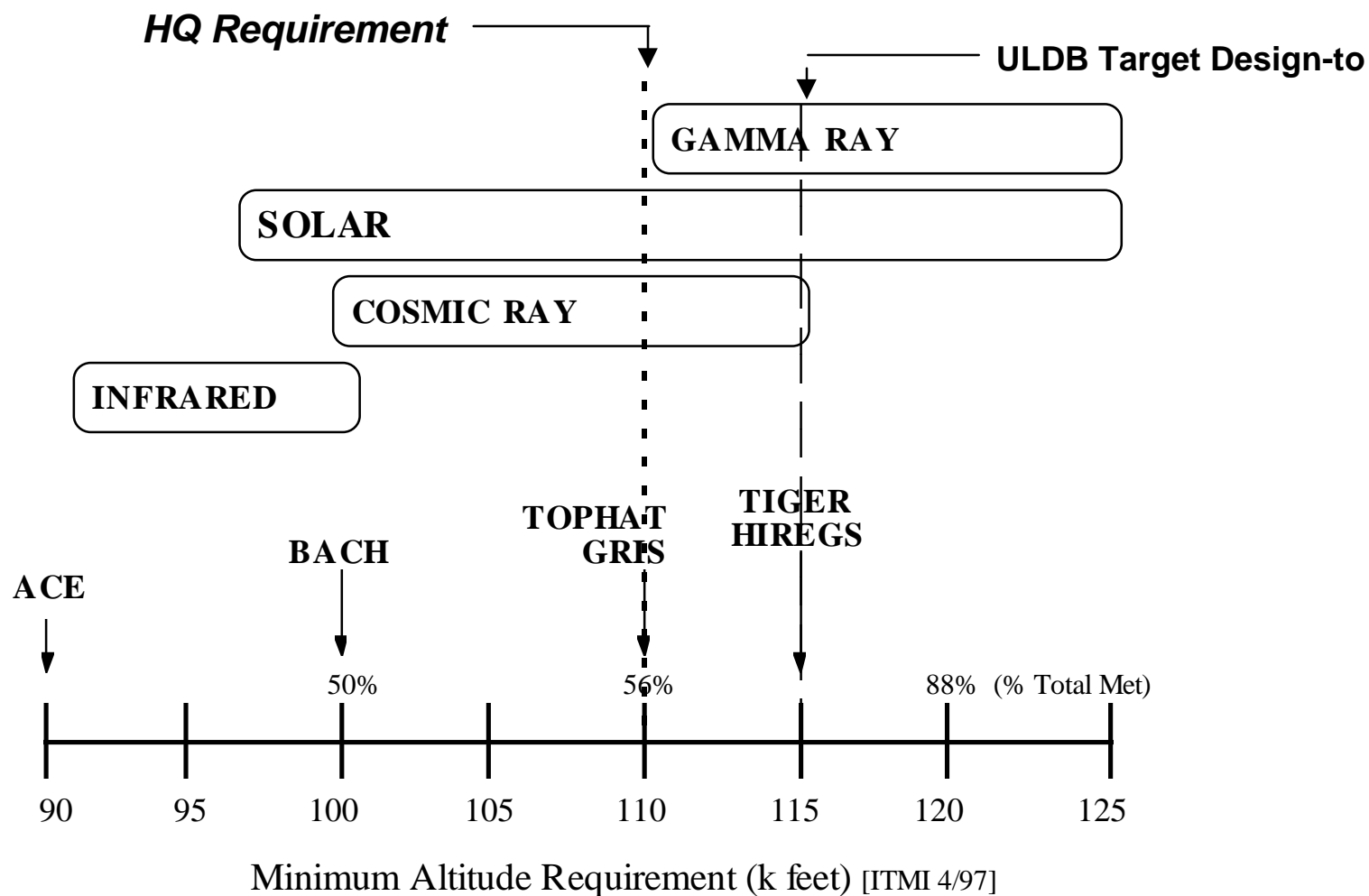




Vehicle Minimum Altitude Requirements

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Vehicle Structure

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- **Leading Design Concepts**
 - Large Super Pressure Balloon
 - Anchor Balloon System
 - Gas Temperature Control
- **Technology Development**
 - Balloon Vehicle Technology Development Research Project
 - » Super Pressure Design
 - » Materials Development
 - » Flight Tests



2.2 *Flight Trajectory Control Systems*

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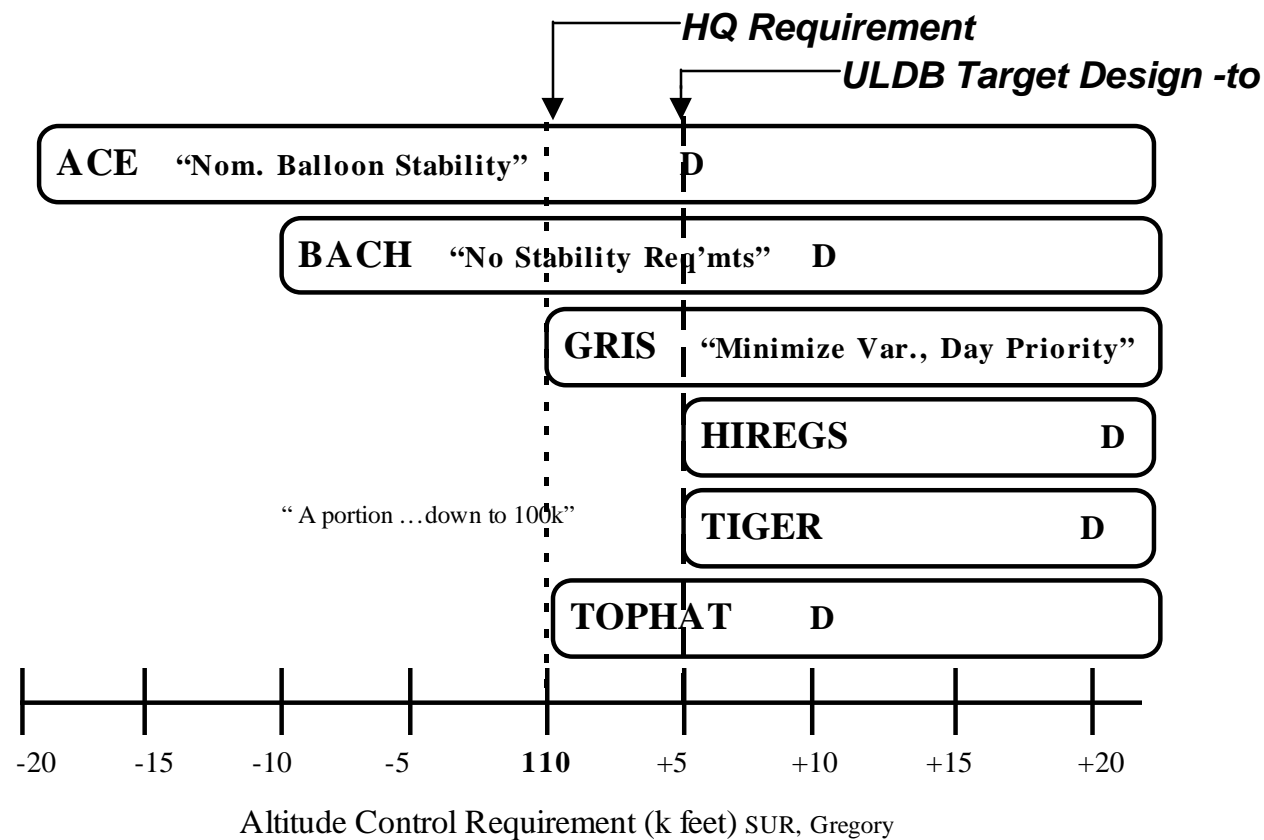
- **Requirements [drivers]**
 - Altitude Control [Mission, Science]
 - Latitude Drift Control [Mission, Science]
- **Target Design-to Requirements**
 - Control Diurnal Altitude Variation to $\leq 10,000'$ (3 km)
 - Control Latitude Drift Variation to $\leq \pm 20$ deg over mission
- **Leading Design Concepts**
 - Altitude
 - » Anchor Balloon
 - » Gas Temperature or Pressure Control
 - Ground Track
 - » Tethered Drag Body
 - » Propulsion



Altitude Control - Science Requirements

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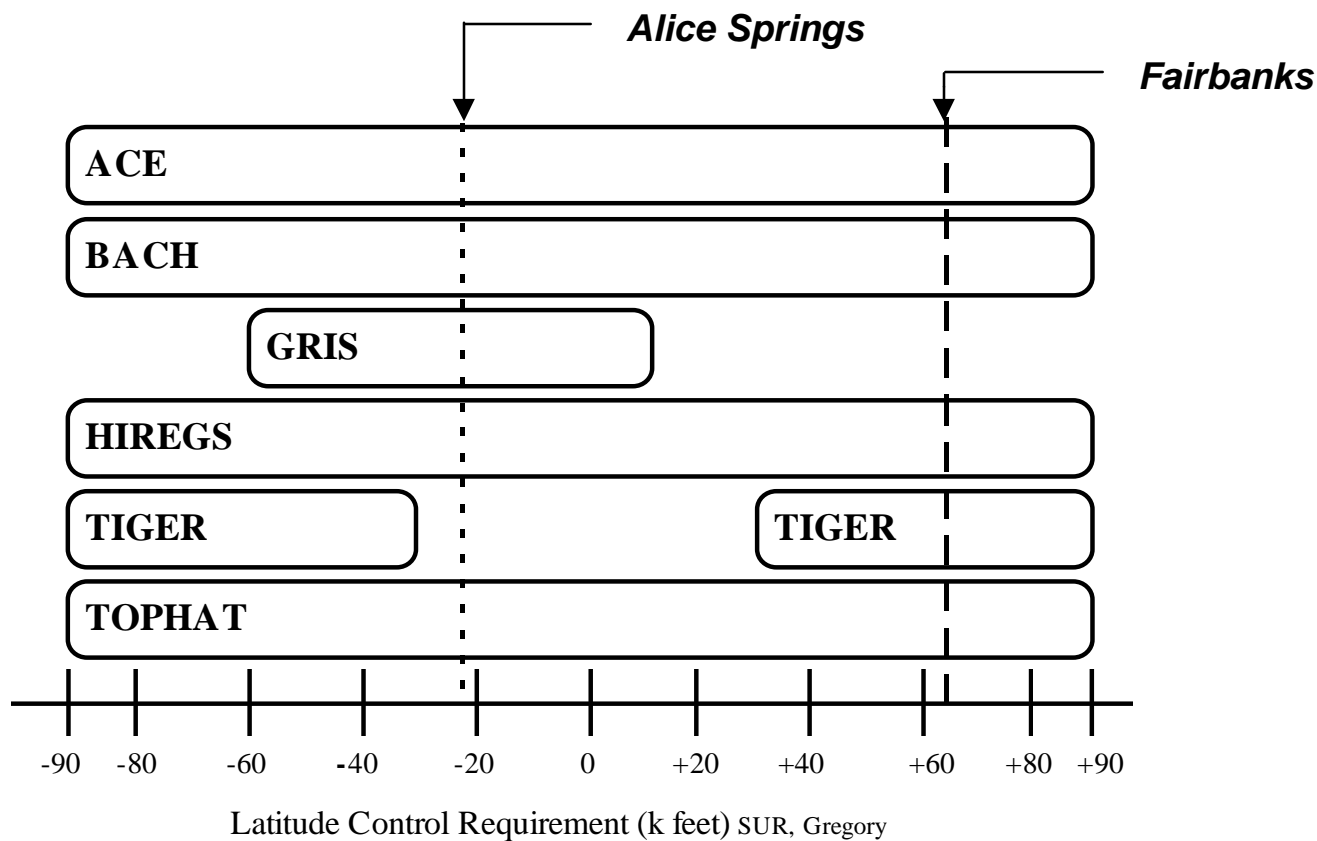


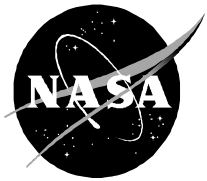


Latitude Control - Science Requirements

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2.2 Flight Trajectory Control Systems

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- **Technology Development**
 - Multiple Altitude Control Systems
 - Multiple Ground Track Control Systems



2.3 Recovery System

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- **Requirements [drvs] *Note: No Science Req'mts***
 - Safely Return Gondola to Surface [Mission]
 - Safely Return Balloon Envelope to Surface [Mission]
- **Target Design-to Requirements**
 - Minimize Payload Damage
 - Provide Water/Land Recovery
- **Leading Design Concepts**
 - Use Current Capability with Terminate Planning
 - Autonomous Steerable Packed Parafoils
 - Inflatables for Impact Shock and Water Recovery
- **Technology Development**
 - Autonomous Steerables Applied to Balloon Mission



2.4 *Flight Train*

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- **Requirements [drivers]**
 - Support Gondola Load, Provide Balloon/Gondola Separation [Mission]
 - Torque Transfer Mechanism [Science, Mission]
- **Target Design-to Requirements**
 - Gondola Load to 3500 lbs (1600 kg)
 - Torsional Stiffness TBD
 - Reduce Terminate Shock Load to $\leq 3g$'s
- **Leading Design Concept**
 - 'Standard' Flight Train with
 - » New Materials
 - » Proven In-line Energy Absorbtion Techniques